

- 1) A harmonic motion has an amplitude of 0.20 cm and a period of 0.15 s . Determine the maximum velocity and acceleration.

$$A = 0.02 \text{ m}$$

$$\tau = 0.15 \text{ s} \Rightarrow \omega = \frac{2\pi}{\tau} = \frac{2\pi}{0.15} \Rightarrow \omega = 41.5 \text{ rad/s}$$

$$\dot{x} = \omega A \cos \omega t \Rightarrow \dot{x}_{\max} = \omega A = 41.5 (0.02 \text{ m})$$

$$\dot{x}_{\max} = 0.84 \text{ m/s}$$

$$\ddot{x} = -\omega^2 A \sin \omega t \Rightarrow \ddot{x}_{\max} = \omega^2 A = (41.5)^2 (0.02 \text{ m})$$

$$\Rightarrow \ddot{x}_{\max} = 35 \text{ m/s}^2$$

- 2) A harmonic motion has a frequency of 10 cps ($\text{cps} = \text{cycles per second} = \text{Hz}$) and its maximum velocity is 4.57 m/s . Determine its amplitude, its period, and its maximum acceleration.

$$f = 10 \text{ Hz} \quad \& \quad \omega A = 4.57 \text{ m/s}$$

$$\omega = 2\pi f = 2\pi (10) = 62.8 \text{ rad/s}$$

$$\therefore A = \frac{4.57}{62.8} \Rightarrow A = 0.07 \text{ m}$$

$$\tau = \frac{1}{f} = 0.1 \text{ sec}$$

$$\ddot{x}_{\max} = \omega^2 A = (62.8)^2 (0.07) \Rightarrow \ddot{x}_{\max} = 276.1 \text{ m/s}^2$$

3) A machine of mass $m=500 \text{ kg}$ is mounted on a simply supported steel beam of length $l = 2 \text{ m}$ having a rectangular cross-section (depth = 0.1 m , width = 1.2 m) and Young's modulus $E=2.06 \times 10^{11} \text{ N/m}^2$. To reduce the vertical deflection of the beam, a spring of stiffness k is attached at the mid-span, as shown below in Figure 1. Determine the value of k needed to reduce the deflection of the beam to one-third of its original value. Assume that the mass of the beam is negligible.

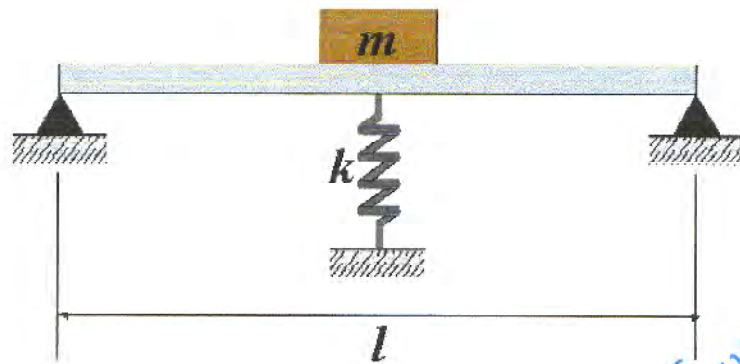


Figure 1

$$I = \frac{(0.1)^3 (1.2)}{12} = 10^{-4} \text{ m}^4$$

For simply supported beam,

$$\text{for load at middle, } k_1 = \frac{48EI}{l^3} = \frac{48(2.06 \times 10^{11})(10^{-4})}{(2)^3}$$

$$k_1 = 12.36 \times 10^7 \text{ N/m}$$

$$\delta_1 = \text{original deflection} = \frac{mg}{k_1} = \frac{500(9.81)}{12.36 \times 10^7}$$

$$\Rightarrow \delta_1 = 396.84 \times 10^{-7} \text{ m}$$

$$\text{New deflection} = \frac{mg}{k_{eq}} = \frac{\delta_1}{3} ; k_{eq} = \frac{3mg}{\delta_1}$$

$$\text{where, } k_{eq} = k + k_1 \quad k_{eq} = \frac{3(500)(9.81)}{396.84 \times 10^{-7}} = 370.8 \text{ kN/m}$$

$$\therefore k = k_{eq} - k_1 = 370.8 - 123.6$$

$$\Rightarrow \boxed{k = 247.2 \text{ kN}}$$

4) Write the equation of motion for the spring-mass system shown in Figure 2. Let its displacement $x(t)$ be measured from:

- the position for which both springs are unstretched. What is the natural frequency of the system?
- the **static equilibrium position** of the system.

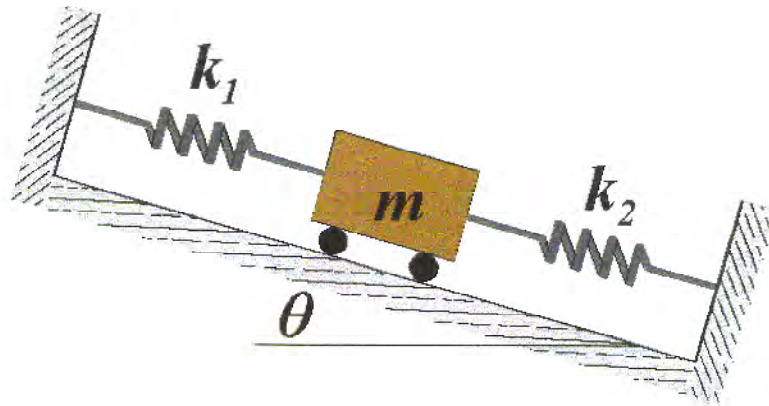


Figure 2

a) Equation of motion:

$$mg \sin \theta - k_1(x + \delta_{st}) - k_2(x + \delta_{st}) = m \ddot{x}$$

But, $\delta_{st}(k_1 + k_2) = W \sin \theta$ (From static equilibrium)

$$\therefore m \ddot{x} + (k_1 + k_2)x = 0 \quad \& \quad \omega_n = \sqrt{\frac{k_1 + k_2}{m}}$$

b) Equation of Motion:

$$-k_1 x - k_2 x = m \ddot{x}$$

$$\therefore m \ddot{x} + (k_1 + k_2)x = 0$$

a) The nature of damping is Viscous damping.

b) $\tau_d = 0.2 \text{ sec}$

$$f_d = 5 \text{ Hz}$$

$$\omega_d = 31.416 \text{ rad/sec}$$

$$c) \frac{x_i}{x_{i+1}} = e^{\zeta \omega_n \tau_d} \Rightarrow \ln \left(\frac{x_i}{x_{i+1}} \right) = \frac{2\pi \zeta}{\sqrt{1-\zeta^2}}$$

$$\ln \left(\frac{x_i}{x_{i+1}} \right) = \ln 2 = 0.6931$$

$$\therefore \frac{2\pi \zeta}{\sqrt{1-\zeta^2}} = 0.6931 \Rightarrow \boxed{\zeta = 0.1096}$$

$$\therefore \omega_d = \omega_n \sqrt{1-\zeta^2}$$

$$\therefore \omega_n = \frac{\omega_d}{\sqrt{1-\zeta^2}} = \frac{31.416}{\sqrt{0.98798}} = 31.61 \text{ rad/sec}$$

$$\therefore \boxed{\omega_n = 31.61 \text{ rad/sec}}$$

$$\therefore \omega_n^2 = \frac{k}{m} \Rightarrow k = m \omega_n^2 = \frac{500}{9.81} (31.61)^2$$

$$\Rightarrow \boxed{k = 50.92 \text{ kN/m}}$$

$$\text{Hence } c = 2 m \omega_n \zeta = 2 \left(\frac{500}{9.81} \right) (31.61) (0.1096)$$

$$\Rightarrow \boxed{c = 353.11 \text{ N.s/m}}$$